Copyright by GRUNER AP @2024_V1. Subject to change in technology and Design.



Technical data sheet

227C-230-16H **Rotary Actuator**

Description

Rotary actuator for adjusting dampers in HVAC installations.

Running time 75 s / 90° Torque NmNominal voltage 230 VAC/DC Control continuous control (0)2...10 VDC Damper size up to approx. 3 m² Damper coupling

♦ 8-15 mm / Ø 8-20 mm



Technical data

Electrical data

Nominal voltage	230 VAC/DC, 50/60Hz	
Nominal voltage range	85265 VAC/DC	
Power consumption motor (motion)	2.5 W	
Power consumption standby (end position)	1.0 W	
Wire sizing	4.0 VA	
Control	continuous control (0)210 VDC	
Connection motor	cable L= 2 x 1000 mm, 4 x 0. 75 mm² & 2 x 0.75 mm² (halogen free)	
Connection feedback potentiometer	-	
Connection GUAC	-	
Feedback signal	0)210 VDC, max. 5 mA	

1



Functional data		
	Torque	16 Nm
	Damper size	up to approx. 3 m²
	Synchronized speed	+/-5%
	Direction of rotation	selected by switch
	Manual override	gearing latch disengaged with pushbutton, self-resetting
	Angle of rotation	0°max. 95° can be limited with adjustable mechanical end stops
	Running Time	75 s / 90°
	Sound power level	< 45 dB(A)
	Shaft coupling	clamp ◊ 8-15 mm / Ø 8-20 mm
	Position indication	mechanical with pointer
	Service life	100,000 cycles (0°95°0°) > 1,500,000 partial cycles (max. ±5°)
Safety		
	Protection class	II (double insulation)
	Degree of protection	IP 54 (cable downwards)
	EMC	CE (2014/30/EU)
	LVD	CE (2014/35/EU)
	RoHS	CE (2011/65/EU - 2015/863/EU - 2017/2102/EU)
	Mode of operation	Typ 1 (EN 60730-1)
	Rated impulse voltage supply / control	0.8 kV (EN 60730-1)
	Control pollution degree	3 (EN 60730-1)
	Ambient temperature normal operation	-30°C+50°C
	Storage temperature	-30°C+80°C
	Ambient humidity	595% r.H., non-condensing (EN 60730-1)
	Maintenance	Maintenance free
Dimensions/Weight		
	Dimensions	117 x 67 x 61 mm
	Weight	350 g



Functionality / Properties

Operating mode

Connect power supply to wire 1+2 and a reference signal Y to wire 3 in range of (0)2...10 VDC, actuator drives to its specified position. The actual damper position (0...100%) is a feedback signal U on wire 4 for example to share with other actuators.

The actuator is overload-proof, requires no limit switches and automatically stops, when the end stop is reached.

Direct mounting

Simple direct mounting on the damper shaft with a clamp, protection against rotating with enclosed anti-rotation lock or rather at intended attachment points.

Manual override

Manual override with self resetting push button possible (the gear is disengaged as long as the button is pressed).

Mode switch

Mode switch with five positions at the housing:

2-10 R: rotary direction right 2-10 VDC

0-10 R: rotary direction right 0-10 VDC

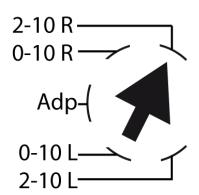
Adp: adaption

0-10 L: rotary direction left 0-10 VDC

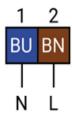
2-10 R: rotary direction left 2-10

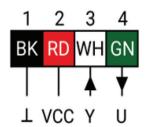
Adaption drive

- · Actuator power off
- Setting the mechanical end stops
- · Actuator power on
- Adaption enable
- Actuator drive to position 0
- Actuator drive to position 1
- Adaption disable, if desired angular range reached or rather if actuator reached endstop
- "Y" refers to the measured angular range



Connector / Security Note





Safety remarks

- Connect via safety isolation transformer.
- The device is not allowed to beused outside the specified field of application, especially inairplanes.
- It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site.
- The device is not allowed to be disposed of as household refuse. All locally valid regulations and requirements mustbe observed.
- When calculating the required torque, the specifications supplied by the damper manufacturer's (cross section, design, installation site), and the air flow conditions must be observed.



Technical Drawing

