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### Technical data sheet

# **363-024-60-S2/8F14 Rotary Actuator**

# **Description**

Rotary actuator for adjusting dampers in HVAC installations.

Running time
Torque
Nominal voltage
Control
150 s / 90°
60 Nm
24V AC/DC
2 -/3-point

Auxiliary switch
 Damper size
 Shaft coupling
 Auxiliary switch
 up to approx. 10 m²
 form fit 14 mm (8F14)



# Technical data

# **Electrical data**

Nominal voltage	24V AC/DC, 50/60Hz	
Nominal voltage range	1929 VAC/DC	
Power consumption motor (motion)	13.5 W	
Power consumption standby (end position)	1.5 W	
Wire sizing	16.5 VA	
Control	2-/3-point	
Feedback signal	-	
Auxiliary switch	2 x SPDT (Ag)	
Contact load	5 (2,5) A, 250 VAC	
Switching point	095°	
Connection motor	cable 1000 mm, 3 x 0.75 mm² (halogen free)	
Connection auxiliary switch	cable 1000 mm, 6 x 0,75 mm² (halogen free)	

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**Functional data** 



Functional data		
	Torque	60 Nm
	Damper size	up to approx. 10 m²
	Synchronized speed	±5%
	Direction of rotation	selected by switch
	Manual override	gearing latch disengaged with pushbutton, self-resetting
	Angle of rotation	0°max. 95°
	Running Time	150 s / 90°
	Sound power level	< 45 dB(A)
	Shaft coupling	form fit 14 mm (8F14)
	Service life	> 60'000 cycles (0° - 95° - 0°)
Safety		
	Protection class	III (safety extra-low voltage)
	Degree of protection	IP 54
	EMC	CE (2014/30/EU)
	LVD	CE (2014/35/EU)
	RoHS	CE (2011/65/EU - 2015/863/EU 2017/2102/EU)
Operarting mode		
	Operating mode	S3-50% ED (EN 60034-1)
	Mode of operation	Typ 1 (EN 60730-1)
	Rated impulse voltage supply / control	0.8 kV (EN 60730-1)
	Control pollution degree	3 (EN 60730-1)
	Ambient temperature normal operation	-30°C+50°C
	Storage temperature	-30°C+80°C
	Ambient humidity	595% r.H., non-condensing (EN 60730-1)
	Maintenance	Maintenance free
Dimensions/Weight		
	Dimensions	193 x 96 x 60 mm
	Weight	1750 g



# **Functionality / Properties**

# Operating mode

### 2 point:

Connect power supply to wire 1+2, actuator drives to position 1. Is also wire 3 connected to the power supply, actuator drives to position 0.

### 3 point:

Connect power supply to wire 1+2, actuator drives to position 1. Is wire 1+3 connected to the power supply, actuator drives to position 0.

The actuator is overload-proof, requires no limit switches and automatically stops, when the end stop is reached.

### **Direct mounting**

Simple direct mounting on the damper shaft with a clamp, protection against rotating with enclosed anti-rotation lock or rather at intended attachment points

### Manual override

Manual override with selfresetting pushbutton possible (the gear is disengaged as long as the button is pressed).

### Signaling

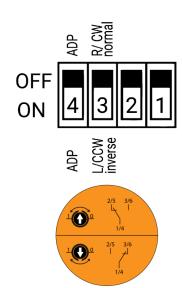
The two integrated auxiliary switches are freely adjustable in the angle of 0 - 95°. There are activated corresponding to the adjusted angle. The damper position can be checked by the mechanicel pointer.

### Mode switch

DIP switch under the case cover

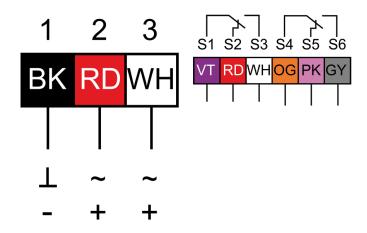
# Adaption drive

- · Actuator power off
- · Setting up the mechanical end stops
- · Actuator power on
- Adaption enable
- Actuator drives to position 0
- Actuator drives to position 1
- Adaption disable, if desired angular range reached or rather if actuator reached endstop





# **Connector / Security Note**

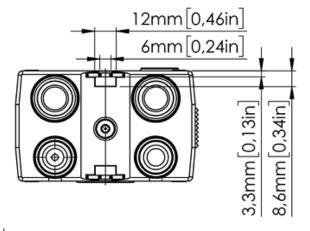


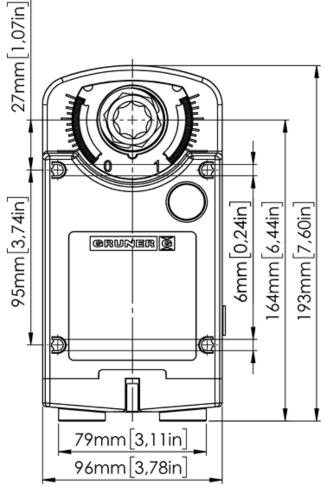
## Safety remarks

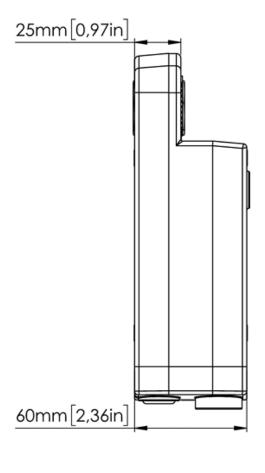
- Connect via safety isolation transformer!
- The device is not allowed to be used outside the specified field of application, especially in airplanes.
- It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site.
- Cables must not be removed from the device.
- The cable of this actuator cannot be replaced. If the cable is damaged, the actuator should be scrapped.
- The device is not allowed to be disposed of as household refuse.
   All locally valid regulations and requirements must be observed.
- When calculating the required torque, the specifications supplied by the damper manufacturer's (cross section, design, installation site), and the air flow conditions must be observed.



# **Technical Drawing**







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