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# Technical data sheet



# 363C-024-60/8F14 Rotary Actuator

# **Description**

Rotary actuator for adjusting dampers in HVAC installations.

Running time
Torque
Nominal voltage
Control
Damper size
Shaft coupling
150 s / 90°
24V AC/DC
continuous control (0)2...10 VDC
up to approx. 10 m²
form fit 14 mm (8F14)



### Technical data

### **Electrical data**

Nominal voltage	24V AC/DC, 50/60Hz	
Nominal voltage range	1929 VAC/DC	
Power consumption motor (motion)	13.5 W	
Power consumption standby (end position)	1.5 W	
Wire sizing	16.5 VA	
Control	continuous control (0)210 VDC /Ri > (100 kΩ) 50 kΩ (0)420 mA	
Feedback signal	(0)210 VDC, max. 5 mA	
Auxiliary switch	-	
Contact load	-	
Switching point	-	
Connection motor	cable 1000 mm, 4 x 0.75 mm² (halogen free)	
Connection auxiliary switch	-	

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Formation of Asso		
Functional data	_	60 N
	Torque	60 Nm
	Damper size	up to approx. 10 m <sup>2</sup>
	Synchronized speed	±5%
	Direction of rotation	selected by switch
	Manual override	gearing latch disengaged with pushbutton, self-resetting
	Angle of rotation	0°max. 95°
	Running Time	150 s / 90°
	Sound power level	< 45 dB(A)
	Shaft coupling	form fit 14 mm (8F14)
	Service life	> 60 000 cycles (0°95°0°) > 1 000 000 partial cycles (max. ±5°)
Safety		
	Protection class	III (safety extra-low voltage)
	Degree of protection	IP 54
	EMC	CE (2014/30/EU)
	LVD	CE (2014/35/EU)
	RoHS	CE (2011/65/EU - 2015/863/EU 2017/2102/EU)
Operarting mode		
	Operating mode	S3-50% ED (EN 60034-1)
	Mode of operation	Typ 1 (EN 60730-1)
	Rated impulse voltage supply / control	0.8 kV (EN 60730-1)
	Control pollution degree	3 (EN 60730-1)
	Ambient temperature normal operation	-30°C+50°C
	Storage temperature	-30°C+80°C
	Ambient humidity	595% r.H., non-condensing (EN 60730-1)
	Maintenance	Maintenance free
Dimensions/Weight		
	Dimensions	193 x 96 x 60 mm
	Weight	1650 g



# **Functionality / Properties**

### Operating mode

Connect power supply to wire 1+2 and a reference signal Y to wire 3 in range of (0)2...10 VDC, actuator drives to its specified position. The actual damper position (0...100%) is a feedback signal U on wire 4 for example to share with other actuators.

The actuator is overload-proof, requires no limit switches and automatically stops, when the end stop is reached.

### **Direct mounting**

Simple direct mounting on the damper shaft with a clamp, protection against rotating with enclosed anti-rotation lock or rather at intended attachment points

### Manual override

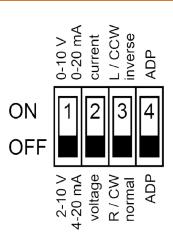
Manual override with selfresetting pushbutton possible (the gear is disengaged as long as the button is pressed).

### Mode switch

DIP switch under the case cover

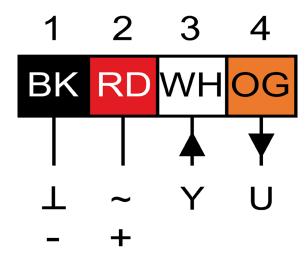
### Adaption drive

- · Actuator power off
- Setting up the mechanical end stops
- Actuator power on
- Adaption enable
- Actuator drives to position 0
- Actuator drives to position 1
- Adaption disable, if desired angular range reached or rather if actuator reached endstop





### **Connector / Security Note**

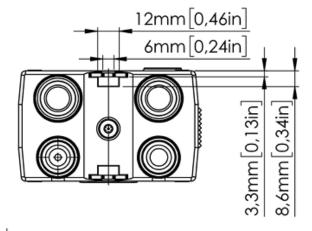


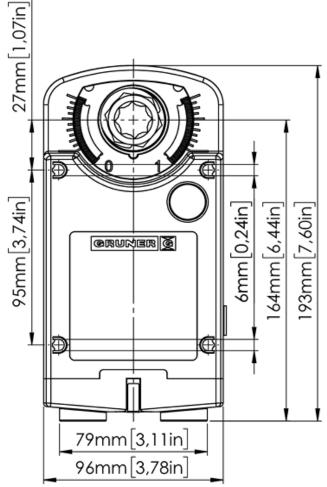
### Safety remarks

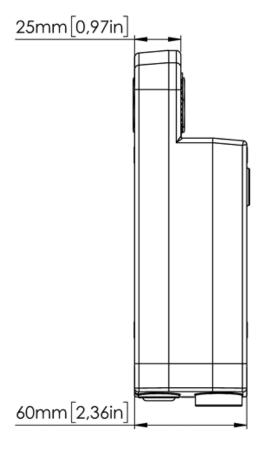
- Connect via safety isolation transformer!
- The device is not allowed to be used outside the specified field of application, especially in airplanes.
- It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site.
- Cables must not be removed from the device.
- The cable of this actuatorcannot be replaced. If the cableis damaged, the actuator should be scrapped.
- The device is not allowed to be disposed of as household refuse.
  All locally valid regulations and requirements must be observed.
- When calculating the required torque, the specifications supplied by the damper manufacturer's (crosssection, design, installation site), and the air flow conditions must be observed.



# **Technical Drawing**







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